

E58 Series

Diameter ϕ 58mm Shaft type/Hollow type/Built-in type Incremental Rotary encoder

Features

- Diameter ϕ 58mm flange type
- Suitable for measuring angle, position, revolution, speed, acceleration and distance
- Power supply : 5VDC, 12–24VDC \pm 5%

⚠ Please read "Caution for your safety" in operation manual before using.



Ordering information

E58SC	10	8000	3	N	24		
Series Diameter ϕ 58mm	Shaft diameter		Pulse/ 1 Revolution	Output phase	Output	Power supply	Cable
SC: Shaft Clamping	External	10 ϕ 10mm	Refer to resolution	2: A, B	T: Totem pole output N: NPN open collector output	5: 5VDC \pm 5% 24: 12–24VDC \pm 5%	Blank: Normal type C: Cable outgoing connector type (250mm) CR: Axial connector integrated type CS: Radial connector integrated type
SS: Shaft Synchro		6 ϕ 6mm		3: A, B, Z (Standard)	V: Voltage output		
H: Hollow	Inner	12 ϕ 12mm		4: A, \bar{A} , B, \bar{B}	L: Line driver output (The power of Line driver is only for 5VDC.)		
HB: Hollow Built-in				6: A, \bar{A} , B, \bar{B} , Z, \bar{Z}			

*Standard: E58SC10–PULSE–3–N–24 *Customizable model specifications are available.

*Standard cable for shaft/built-in encoder is axial connector type cable.
Standard cable for hollow shaft encoder is radial connector type cable.

Specifications

Item	Diameter ϕ 58mm incremental rotary encoder	
Resolution (P/R)	(Note1) *1, *2, *5, 10, *12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 125, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 5000, 6000, 8000	
Output phase	A, B, Z phase (Line driver output : A, \bar{A} , B, \bar{B} , Z, \bar{Z} phase)	
Phase difference of output	Phase difference between A and B phase : $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)	
Control output	Totem pole output	• Low \Rightarrow Load current : Max. 30mA, Residual voltage : Max. 0.4VDC • High \Rightarrow Load current : Max. 10mA, Output voltage (Power voltage 5VDC) : Min. (Power voltage–2.0)VDC, Output voltage (Power voltage 12–24VDC) : Min. (Power voltage–3.0)VDC
	NPN open collector output	Load current : Max. 30mA, Residual voltage : Max. 0.4VDC
	Voltage output	Load current : Max. 10mA, Residual voltage : Max. 0.4VDC
	Line driver output	• Low \Rightarrow Load current : Max. 20mA, Residual voltage : Max. 0.5VDC • High \Rightarrow Load current : Max. –20mA, Output voltage : Min. 2.5VDC
	Res–response time (Rise/Fall)	Totem pole output
	NPN open collector output	
	Voltage output	
	Line driver output	Max. 0.5 μ s (Cable length: 2m, I sink=20mA)
Max. Response frequency	300kHz	
Power supply	• 5VDC \pm 5% (Ripple P–P : Max. 5%) • 2–24VDC \pm 5% (Ripple P–P : Max. 5%)	
Current consumption	Max. 80mA (disconnection of the load), Line driver output : Max. 50mA (disconnection of the load)	
Insulation resistance	Min. 100M Ω (at 500VDC mega for all terminals and case)	
Dielectric strength	750VAC 50/60Hz for 1 minute (all terminals and case)	
Connection	Cable outgoing type, Cable outgoing connector type, Connector integrated type (axial, radial)	
Mechanical specification	Starting torque	• SC/SS type : Max. 40gf \cdot cm (0.004N \cdot m) • HB/H type : Max. 90gf \cdot cm (0.009N \cdot m)
	Moment of inertia	• SC/SS type : Max. 15g \cdot cm ² (1.5 \times 10 ^{–6} kg \cdot m ²) • HB/H type : Max. 20g \cdot cm ² (2 \times 10 ^{–6} kg \cdot m ²)
	Shaft loading	• SC/SS type \Rightarrow Max. Radial : 10kg \cdot f, Thrust : Max. 2.5kg \cdot f • HB/H type \Rightarrow Max. Radial : 2kg \cdot f, Thrust : Max. 1kg \cdot f
	Max. allowable revolution	(Note2) 5000rpm
Vibration	1.5mm amplitude at frequency of 10 to 55Hz (for one minute cycle) in each of X, Y, Z directions for 2 hours	
Shock	Max. 75G	
Ambient temperature	–10 to 70 $^{\circ}$ C (at non–freezing status), Storage : –25 to 85 $^{\circ}$ C	
Ambient humidity	35 to 85%RH, Storage : 35 to 90%RH	
Protection	IP50 (IEC standard)	
Cable	ϕ 5mm, 5P, Length : 2m, Shield cable (Line driver output : ϕ 5mm, 8P)	
Accessory	ϕ 10mm (SC type) / ϕ 6mm (SS type) coupling, Fixing bracket	
Approval	CE (Except Line driver output)	
Unit weight	• SC–CS/CR type: Approx. 230g, SS–CS/CR type: Approx. 205g, HB–CS/CR type: Approx. 200g • SC type: Approx. 310g, SS type: Approx. 285g, HB type: Approx. 270g, H type: Approx. 270g	

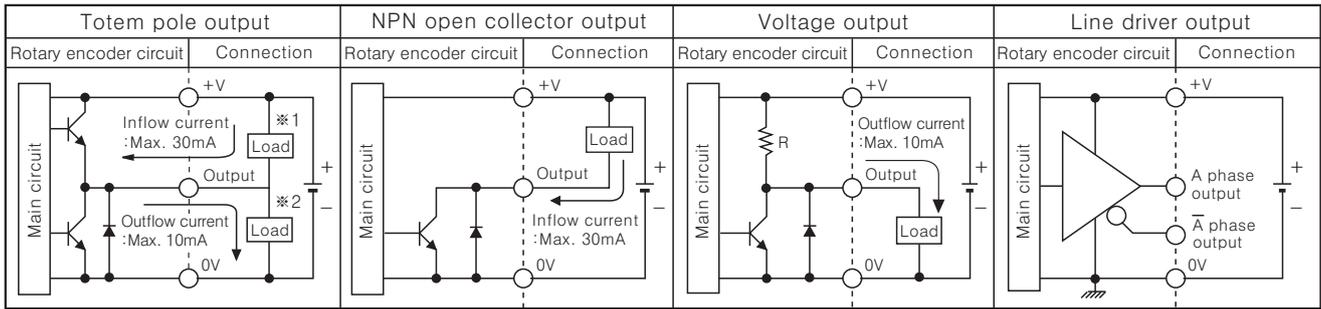
***(Note1)** 1, 2, 5 12 P/R output A and B phase only. (But Line driver output : A, \bar{A} , B, \bar{B} phase) [In case of hollow shaft type, 6000, 8000 P/R excluded]

***(Note2)** Max. allowable revolution \geq Max. response revolution **[Max. response revolution (rpm) = $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec.}$]**

Please select the resolution to make max. revolution lower than max. allowable revolution.

Incremental ϕ 58mm Shaft/Hollow Shaft/Built-in Type

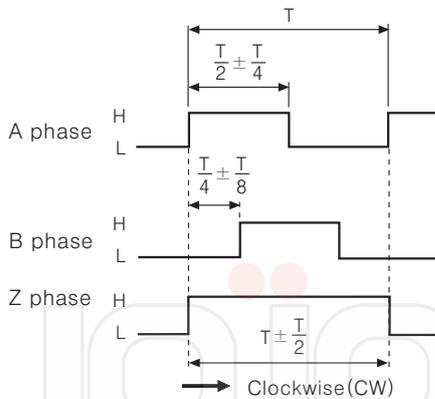
Control output diagram



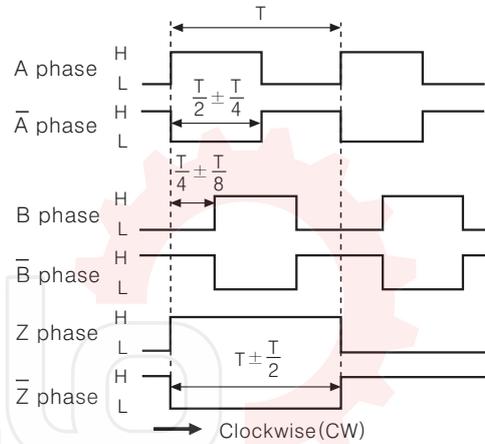
- Totem pole output type can be used for NPN open collector output type (*1) or Voltage output type (*2).
- All output circuits of A, B, Z phase are the same. (Line driver output is A, \bar{A} , B, \bar{B} , Z, \bar{Z})

Output waveform

- Totem pole output / NPN open collector output / Voltage output
- Line driver output



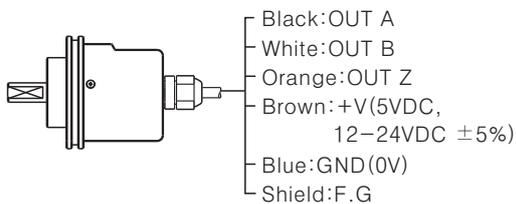
*CW : Right turn as from the shaft



Connections

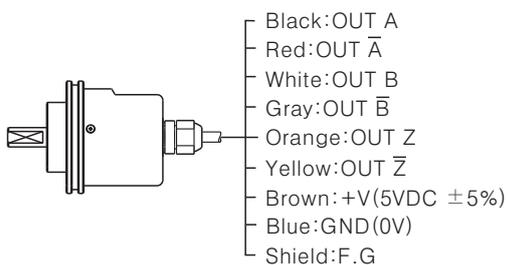
Normal type

- Totem pole output / NPN open collector output / Voltage output



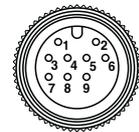
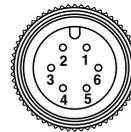
- Unused wires must be insulated.
- The metal and shield cable of encoder should be grounded(F.G)

- Line driver output



Cable outgoing connector/ Connector integrated type

- Totem pole output
- NPN open collector output
- Voltage output
- Line driver output



Totem pole output NPN open collector output Voltage output			Line driver output		
Pin No	Function	Cable color	Pin No	Function	Cable color
①	OUT A	Black	①	OUT A	Black
②	OUT B	White	②	OUT \bar{A}	Red
③	OUT Z	Orange	③	+V	Brown
④	+V	Brown	④	GND	Blue
⑤	GND	Blue	⑤	OUT B	White
⑥	F.G	Shield	⑥	OUT \bar{B}	Gray
			⑦	OUT Z	Orange
			⑧	OUT \bar{Z}	Yellow
			⑨	F.G	Shield

*F.G(Field Ground) : It should be grounded separately.

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/Socket

(H) Temp. controller

(I) SSR/Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/Speed/Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/Logic panel

(S) Field network device

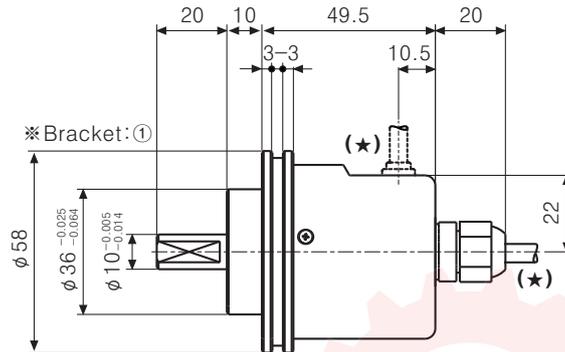
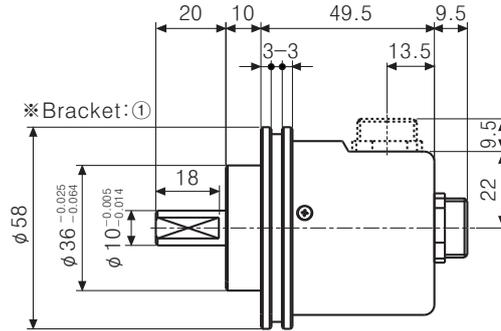
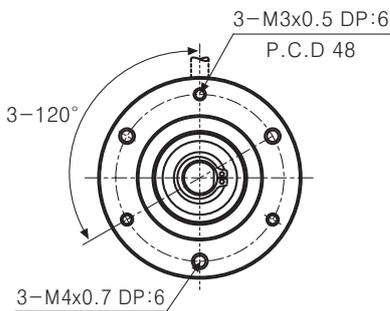
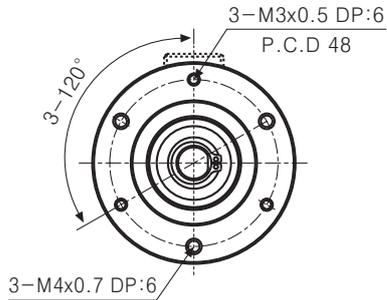
(T) Production stoppage models & replacement

E58 Series

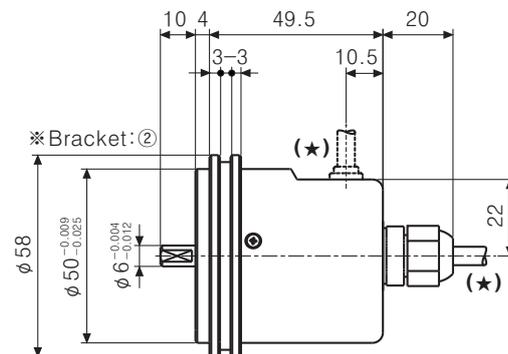
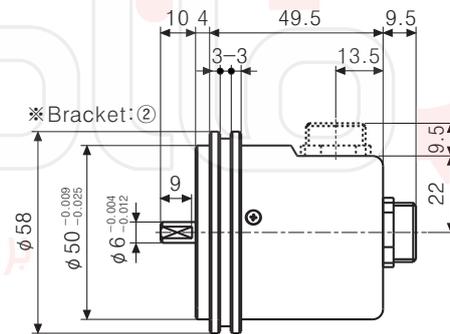
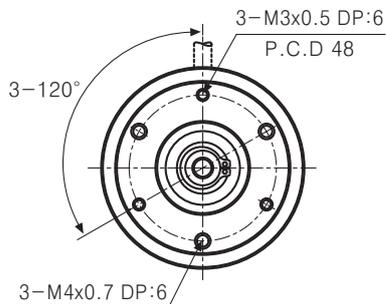
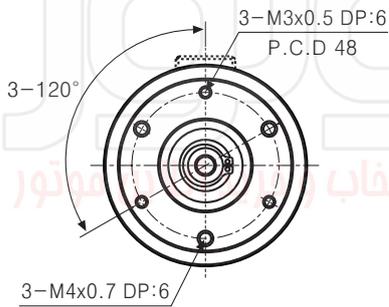
■ Dimensions

(Unit:mm)

■ Shaft clamping type

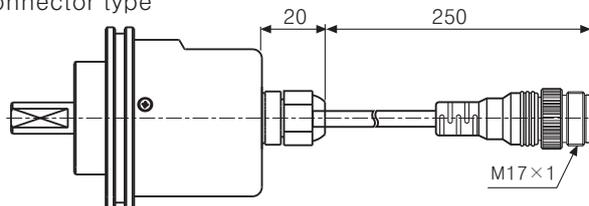


■ Shaft synchro type



※ (★) Cable for normal type
 ϕ 5mm, 5P (Line driver output: 8P),
 Length: 2000, Shield cable

● Cable outgoing connector type

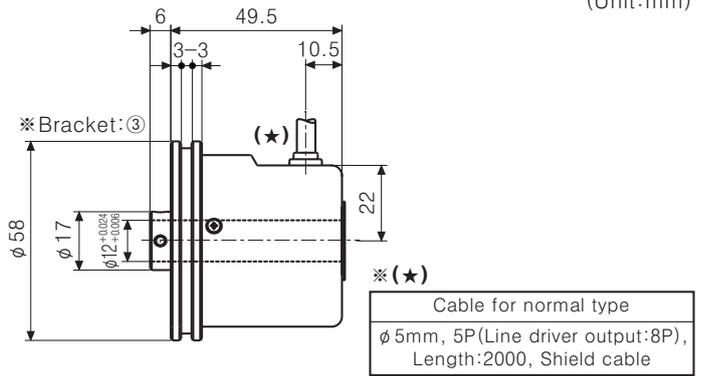
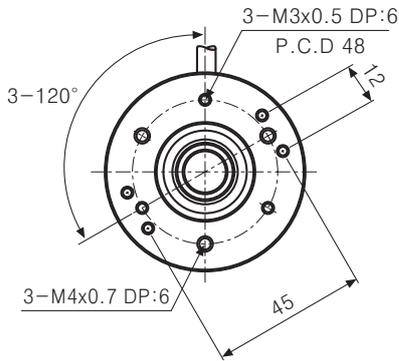


※ Connector cable is customizable and see G-6 for specifications.

Incremental $\phi 58\text{mm}$ Shaft/Hollow Shaft/Built-in Type

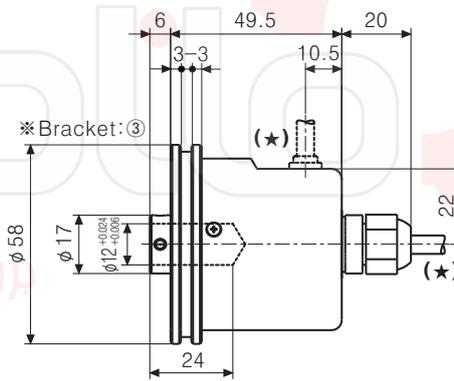
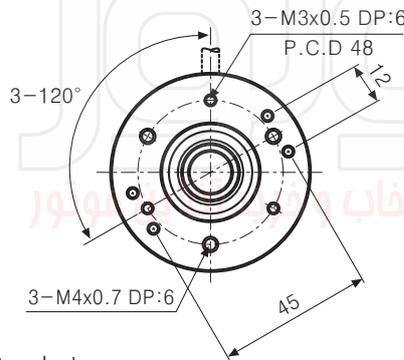
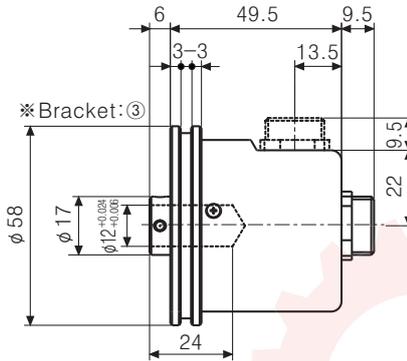
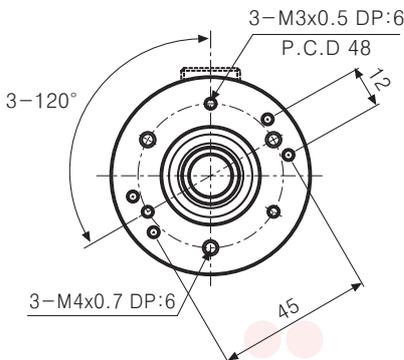
Dimensions

Hollow type



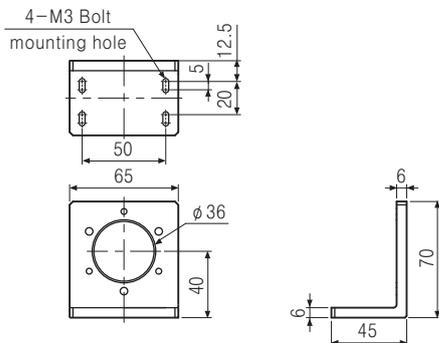
(Unit:mm)

Hollow built-in type

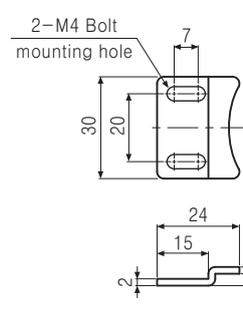


Bracket

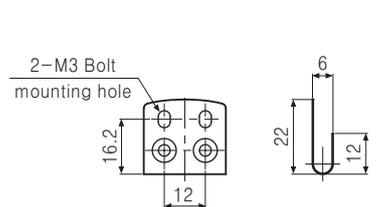
SC type: ①



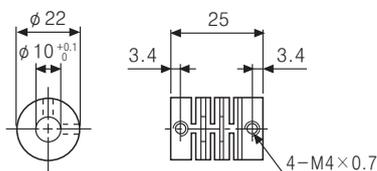
SS type: ②



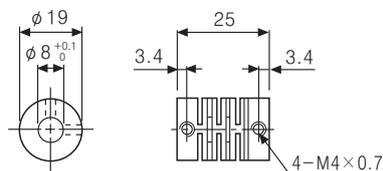
HB/H type: ③



$\phi 10$ Coupling (E58SC10 Series)



$\phi 8$ Coupling (E58SS6 Series)



- (A) Photo electric sensor
- (B) Fiber optic sensor
- (C) Door/Area sensor
- (D) Proximity sensor
- (E) Pressure sensor
- (F) Rotary encoder
- (G) Connector/Socket
- (H) Temp. controller
- (I) SSR/Power controller
- (J) Counter
- (K) Timer
- (L) Panel meter
- (M) Tacho/Speed/Pulse meter
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- (T) Production stoppage models & replacement