

Incremental ϕ 80mm Hollow Shaft Type

Diameter ϕ 80mm Hollow shaft type Incremental Rotary encoder

■ Features

- Diameter ϕ 80mm, Inner diameter of shaft ϕ 30mm, ϕ 32mm (Customizable)
- Allows to install directly at motor or machinery without coupling
- Power supply : 5VDC, 12–24VDC $\pm$ 5%
- Various output types

⚠ Please read "Caution for your safety" in operation manual before using.



■ Ordering information

E80H	30	3200	3	N	24	
Series	Shaft diameter	Pulse/1 Revolution	Output phase	Output	Power supply	Cable
Diameter ϕ 80mm, hollow shaft type	ϕ 30mm ϕ 32mm	60, 100, 360, 500, 512, 1024, 3200	3 : A, B, Z 6 : A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$	T : Totem pole output N : NPN open collector output V : Voltage output L : Line driver output(*)	5 : 5VDC $\pm$ 5% 24 : 12–24VDC $\pm$ 5%	Blank : Normal type (*) C : Cable outgoing connector type

☞ Shaft inner diameter ϕ 32mm is customizable.

*The power of Line driver is only for 5VDC

*Cable length : 250mm

■ Specifications

Item		Diameter ϕ 80mm hollow shaft type of incremental rotary encoder	
Resolution (P/R)		(Note1)	60, 100, 360, 500, 512, 1024, 3200
Electrical specification	Output phase	A, B, Z phase (Line driver output A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$ phase)	
	Phase difference of output	Phase difference between A and B : $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)	
	Control output	Totem pole output	• Low ☞ Load current: Max. 30mA, Residual voltage : Max. 0.4VDC • High ☞ Load current: Max. 10mA, Output voltage (Power supply 5VDC): Min. (Power supply – 2.0)VDC, Output voltage (Power supply 12–24VDC): Min. (Power supply – 3.0)VDC
		NPN open collector output	Load current : Max. 30mA, Residual voltage : Max. 0.4VDC
		Voltage output	Load current : Max. 10mA, Residual voltage : Max. 0.4VDC
		Line driver output	• Low ☞ Load current : Max. 20mA, Residual voltage : Max. 0.5VDC • High ☞ Load current : Max. –20mA, Output voltage : Min. 2.5VDC
	Response time (Rise/Fall)	Totem pole output	Max. 1 μ s
		NPN open collector output	Max. 1 μ s
		Voltage output	Max. 1 μ s
		Line driver output	Max. 0.5 μ s
	Max. Response frequency	200kHz	
	Power supply	• 5VDC $\pm$ 5% (Ripple P–P: Max. 5%) • 12–24VDC $\pm$ 5% (Ripple P–P: Max. 5%)	
	Current consumption	Max. 80mA (disconnection of the load), Line driver output: Max. 50mA (disconnection of the load)	
	Insulation resistance	Min. 100M Ω (at 500VDC megger between all terminals and case)	
	Dielectric strength	750VAC 50/60Hz for 1 minute (Between all terminals and case)	
	Connection	Cable outgoing type, 250mm cable outgoing connector type	
Mechanical specification	Starting torque	Max. 200gf · cm (0.02N · m)	
	Moment of inertia	Max. 800g · cm ² (8×10^{-5} kg · m ²)	
	Shaft loading	Radial : 5kgf, Thrust : 2.5kgf	
	Max. allowable revolution	(Note2)	3600rpm
Vibration		1.5mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hours	
Shock		Max. 75G	
Ambient temperature		–10 to 70°C (at non-freezing status), Storage : –25 to 85°C	
Ambient humidity		35 to 85%RH, Storage : 35 to 90%RH	
Protection		IP50 (IEC standard)	
Cable		ϕ 5mm, 5P, Length : 2m, Shield cable (Line driver output : ϕ 5mm, 8P)	
Accessory		Spring bracket	
Unit weight		Approx. 560g	
Approval		CE (Except for line driver output)	

* (Note1) Not indicated type is customizable.

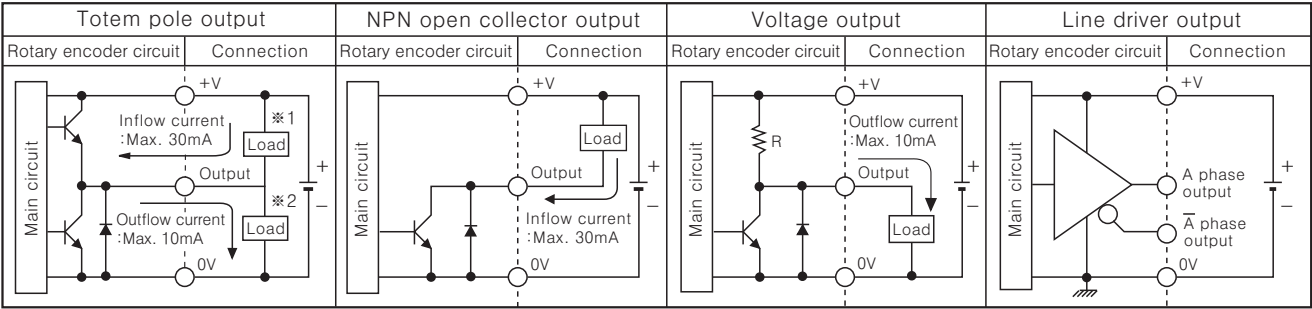
* (Note2) Max. allowable revolution $\geq$ Max. response revolution $\left[\text{Max. response revolution (rpm)} = \frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec.} \right]$

Make sure that max. response revolution should be lower than max. allowable revolution when selecting the resolution.

(A)	Photo electric sensor
(B)	Fiber optic sensor
(C)	Door/Area sensor
(D)	Proximity sensor
(E)	Pressure sensor
(F)	Rotary encoder
(G)	Connector/Socket
(H)	Temp. controller
(I)	SSR/Power controller
(J)	Counter
(K)	Timer
(L)	Panel meter
(M)	Tacho/Speed/Pulse meter
(N)	Display unit
(O)	Sensor controller
(P)	Switching power supply
(Q)	Stepping motor & Driver & Controller
(R)	Graphic/Logic panel
(S)	Field network device
(T)	Production stoppage models & replacement

E80H Series

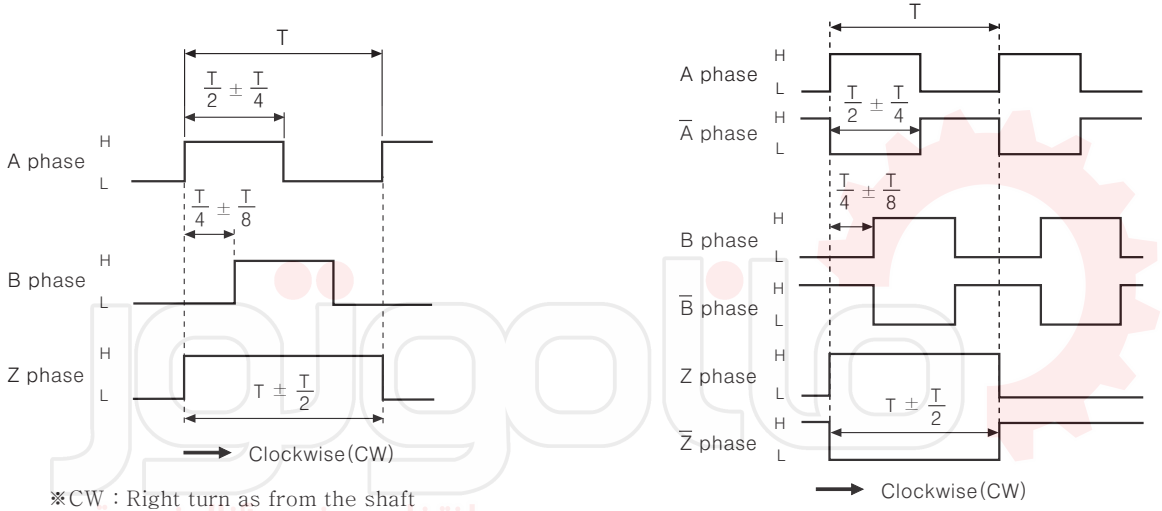
Control output diagram



- Totem pole output type can be used for NPN open collector output type(※1) or Voltage output type(※2).
- All output circuits of A, B, Z phase are the same. (Line driver output is A, $\bar{A}$, B, $\bar{B}$, Z, $\bar{Z}$)

Output waveform

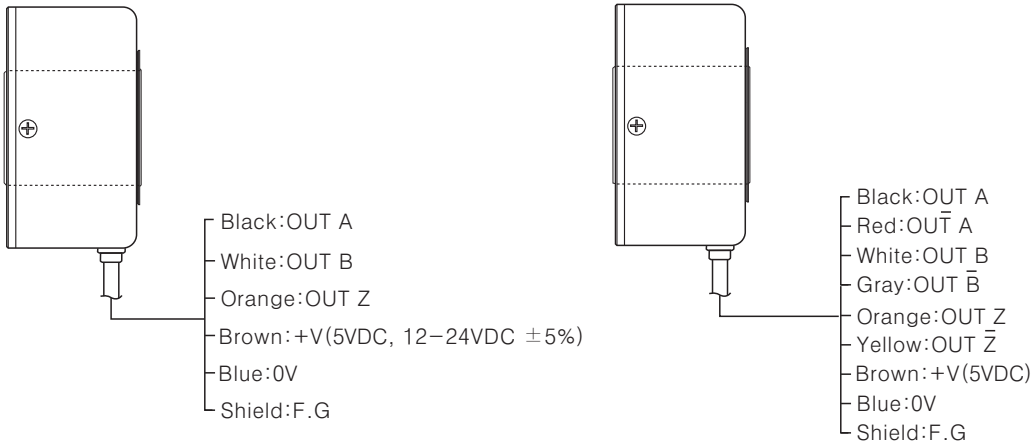
- Totem pole output / NPN open collector output / Voltage output
- Line driver output



Connections

Normal type

- Totem pole output / NPN open collector output / Voltage output
- Line driver output



- ※Unused wires must be insulated.
- ※The metal case and shield cable should be grounded(F.G).

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■ Connection

■ Cable outgoing connector type

- Totem pole output / NPN open collector output / Voltage output



- Line driver output



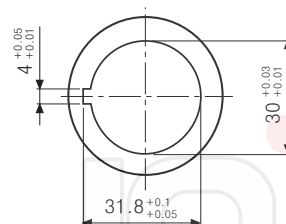
Totem pole output NPN open collector output Voltage output			Line driver output		
Pin No	Function	Cable color	Pin No	Function	Cable color
①	OUT A	Black	①	OUT A	Black
②	OUT B	White	②	OUT $\bar{A}$	Red
③	OUT Z	Orange	③	+V	Brown
④	+V	Brown	④	GND	Blue
⑤	GND	Blue	⑤	OUT B	White
⑥	F.G	Shield	⑥	OUT $\bar{B}$	Gray
			⑦	OUT Z	Orange
			⑧	OUT $\bar{Z}$	Yellow
			⑨	F.G	Shield

※F.G(Field Ground) : It should be grounded separately.

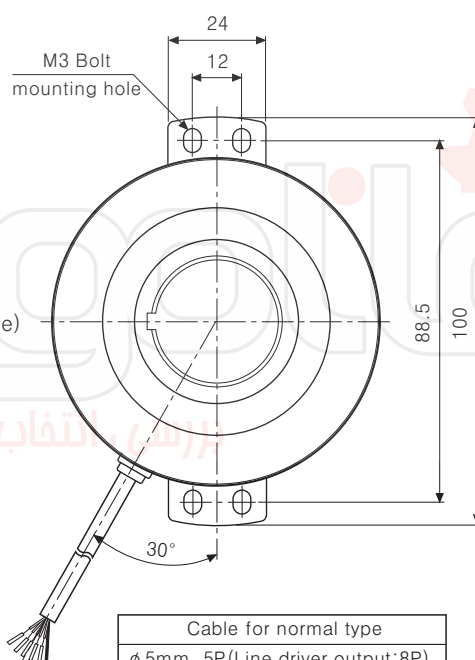
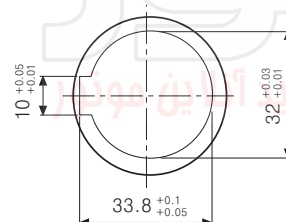
■ Dimensions

■ Normal type

- Inner diameter of shaft(Standard)



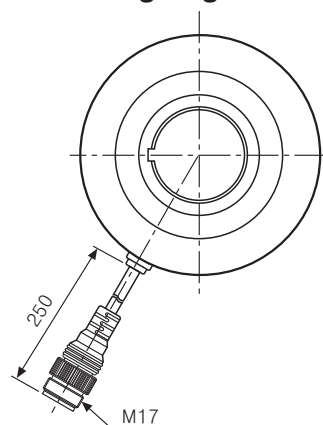
- Inner diameter of shaft(Customizable)



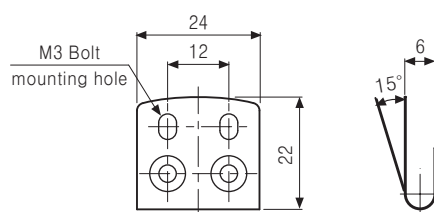
Cable for normal type
 $\phi 5\text{mm}$, 5P(Line driver output:8P),
 Length:2000m, Shield cable

(Unit:mm)

■ Cable outgoing connector type



- Bracket



※Connector cable is customizable and see G-6 for specifications.

(A)	Photo electric sensor
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