

EPM50 SERIES

Diameter ϕ 50mm Shaft type Absolute Multi-turn Rotary encoders

NEW

■ Features

- Compact size of diameter ϕ 50mm
- Parallel data / SSI data transmission type
- **Total 23bit resolution(8388608 divisions) of 10bit single-turn(1024 divisions) and 13bit multi-turn (8192 divisions)**
- Easy zero adjustment using single-turn / multi-turn data separated reset function
- Memorizing revolution data up to $\pm 90^\circ$ after blackout without memory back up function
- Possible CW/CCW direction setting with direction function
- Maximizing users convenience with lclear, overflow alarm (OVF) function
- Protection structure IP64 (Partial waterproof, Oil proof)
- Provides Latch fuction (Parallel output model only)



■ Applications

Precision machine tool, Fabric machinery, Robot, Parking system

⚠ Please read "Caution for your safety" in operation manual before using.



■ Ordering information

EPM50S	8	—	10	13	—	B	—	PN	—	24
Series	Shaft diameter		Single—turn	Multi—turn		Output code		Control output		Power supply
Diameter ø 50mm	ø 8mm		10bit (1024 division)	13bit (8192 division)		Binary Code		PN:Parallel NPN open collector output S—SSI		12—24VDC ±5%

■ Specifications

Type		ø 50mm Multi-turn absolute encoder		
Model		EPM50S8-1013-B-S-24	EPM50S8-1013-B-PN-24	
Resolution	Single-turn	1024 division (10Bit)		
	Multi-turn	8192 revolution (13Bit)		
Rotation limit when power is off		(★1) ± 90°		
Electrical specification	Output	Output code	24bit, Binary 2 code	Binary 2 code
		Output Interface	SSI(Synchronous Serial Interface)	Parallel
		Output type	Line driver	NPN open collector output
		Output signal	Single-turn data, Multi-turn count, (★2) OVF alarm	
		Line driver output	• Low: Sink current – max. 20mA, Residual voltage – max. 0.5VDC • High: Sink current – max. -20mA, Output voltage – max. 2.5VDC	————
		NPN open collector output	————	Sink current : Max. 32mA, Residual voltage : Max. 1VDC
		Logic	————	Negative logic output
		Response time	————	Max. 1μs (Cable: 2m, I sink = 32mA)
	Input	Input signal	(★3) Single-turn data reset, (★4) Multi-turn count reset, Direction, Clear	
			————	Latch
		Input level	High : 5-24VDC, Low : 0-1.2VDC	
		Input logic	(★5) Low active, HIGH or OPEN for common use	
		Input time	Direction : Over 100ms	
			Single-turn data reset : Over 100ms	
Multi-turn count reset : Over 100ms				
Clear : Over 100ms				
	No Latch function	Latch : Over 500μs		
SSI Clock Input Frequency	100kHz to 1MHz		————	

※ **(★1)** It calibrates the multi-turn counts by comparing single-turn data before/after power off without counting multi-turn counts when power is off. It shall be used on the condition that no over-rated revolution occurred since proper multi-turn data may not be available if any revolutions occurred over $\pm 90^\circ$ from the position when power is off.

※ **(★2)** OVF alarm is ON when multi-turn count is out of counting range (0 to 8191 revolution).

It shall be initialized by changing the setting of direction or applying multi-turn count reset or clear signals.

※ **(★3)** Single-turn data shall be initialized as 「0」 when single-turn data reset is input.

※ **(★4)** Multi-turn count shall be initialized as 「0 revolution」 when multi-turn count reset is input.

※ **(★5)** High active is customizable.

ϕ 50mm Shaft Multi-turn Absolute Type

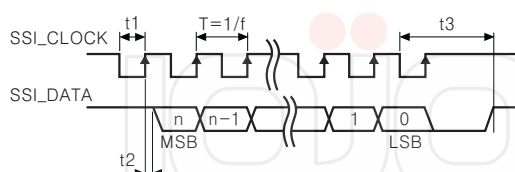
■ Specifications

Type	ϕ 50mm Multi-turn absolute encoder	
Model	EPM50S8-1013-B-S-24	EPM50S8-1013-B-PN-24
Electrical specification	Max. Response frequency	50kHz
	Power supply	12-24VDC, $\pm 5\%$ (Ripple P-P : Max. 5%)
	Current consumption	Max. 150mA (Disconnection of the load) Max. 100mA (Disconnection of the load)
	Insulation resistance	Min. 100M Ω (At 500VDC between all terminals and case)
	Dielectric strength	750VAC 50/60Hz for 1 minute (Between all terminals and case)
Mechanical specification	Connection	Cable outgoing type (Cable gland)
	Starting torque	Max. 40gf $\cdot$ cm (0.004N $\cdot$ m)
	Moment of inertia	Max. 40g $\cdot$ cm ² (4×10^{-6} kg $\cdot$ m ²)
	Shaft loading	Radial : 10kgf, Thrust : 2.5kgf
	Max. revolution	(★6) 3000rpm
Vibration	1.5mm amplitude at frequency of 10 to 55Hz (for one minute cycle) in each of X, Y, Z direction for 2 hours	
Shock	Max. 50G	
Ambient temperature	-10 to 70°C (At non-freezing status), Storage : -25 to 85°C	
Ambient humidity	35 to 85%RH	
Protection	IP64 (IEC standard)	
Cable	ϕ 6mm 10P, Length : 2m, Shield cable	ϕ 6mm 17P $\times$ 2, Length : 2m, Shield cable
Accessory	Mounting bracket, Coupling	
Approval	CE	
Unit weight	Approx. 322g	Approx. 475g

※ (★6) In case of Parallel type model, select the resolution to make max. response revolution is lower than max. allowable revolution.

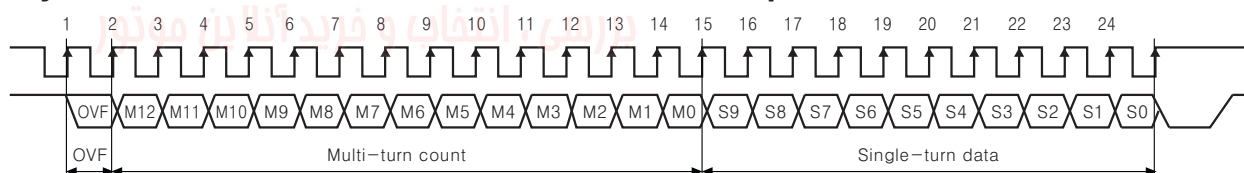
$$\text{【Max. Response Revolution (rpm) = } \frac{\text{Max. Allowable Revolution}}{\text{Resolution}} \times 60 \text{ sec.】}$$

■ Synchronous serial interface (SSI) Output Timing diagram



Clock Frequency f	100kHz to 1MHz
T	T : 1 to 10 μ s
Time lag t2	0.5 μ s < t2 < 5 μ s
Monoflop Time t3	15 μ s < t3 < 30 μ s

■ Synchronous serial interface (SSI) Data Output



Clock input bit	Data output name	Data output bit	Clock input bit	Data output name	Data output bit
1	Over flow error bit	0 bit	15	Single-turn data	9 bit (MSB)
2	Multi-turn count	12 bit (MSB)	16		8 bit
3		11 bit	17		7 bit
4		10 bit	18		6 bit
5		9 bit	19		5 bit
6		8 bit	20		4 bit
7		7 bit	21		3 bit
8		6 bit	22		2 bit
9		5 bit	23		1 bit
10		4 bit	24		0 bit (LSB)
11		3 bit			
12		2 bit			
13		1 bit			
14		0 bit (LSB)			

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/Socket

(H) Temp. controller

(I) SSR/Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/Speed/Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

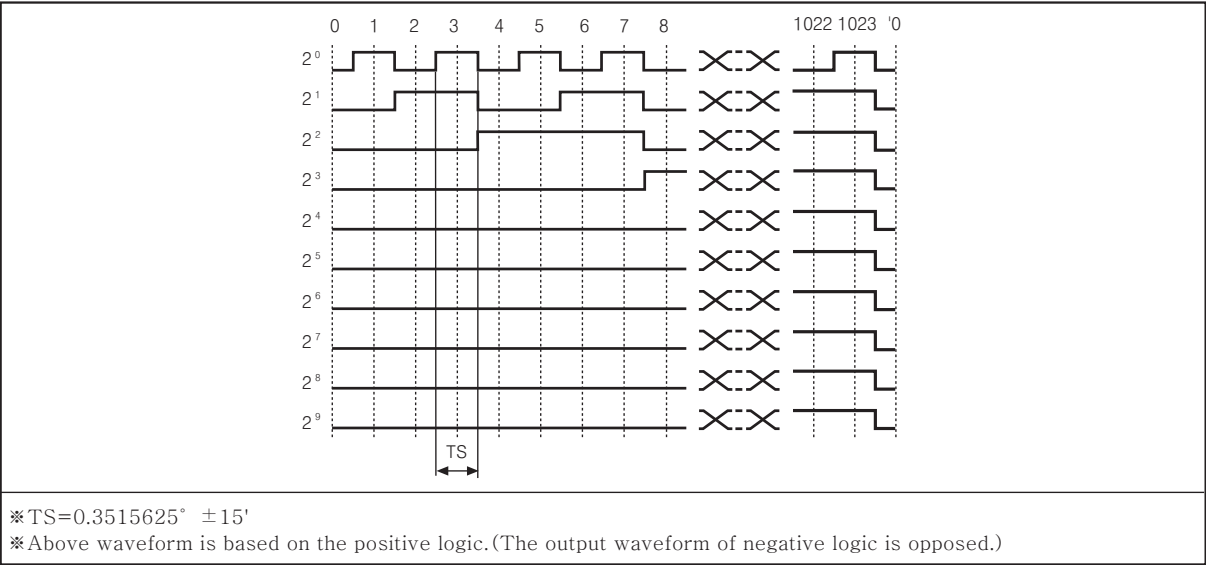
(R) Graphic/Logic panel

(S) Field network device

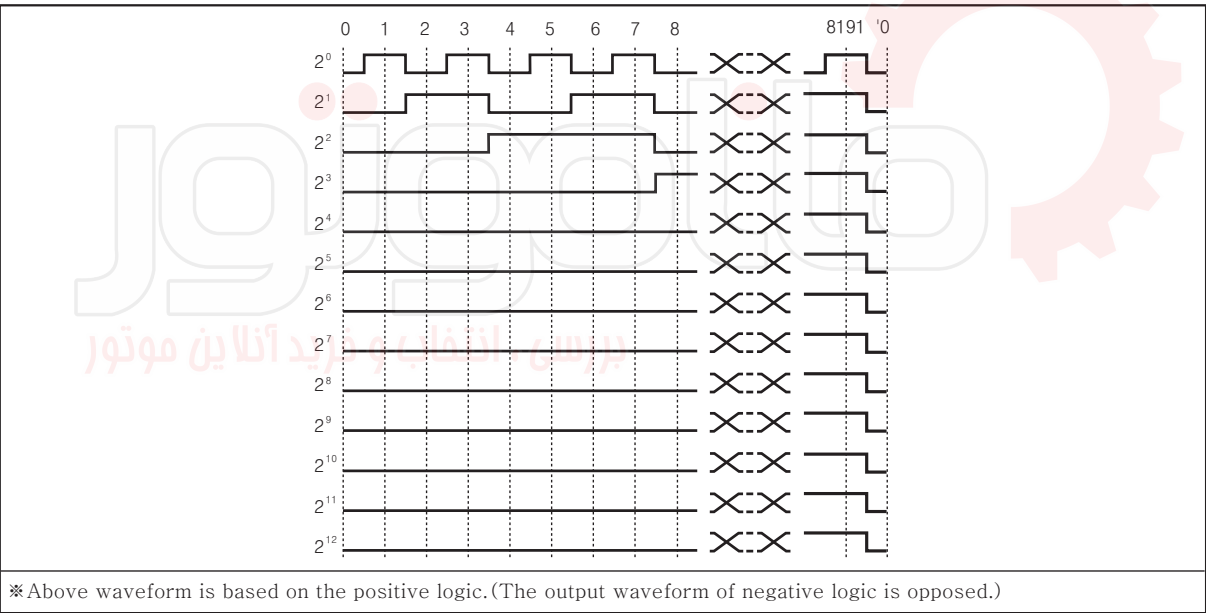
(T) Production stoppage models & replacement

EPM50 SERIES

Parallel Interface 1024 division single-turn data output waveform (Binary code)

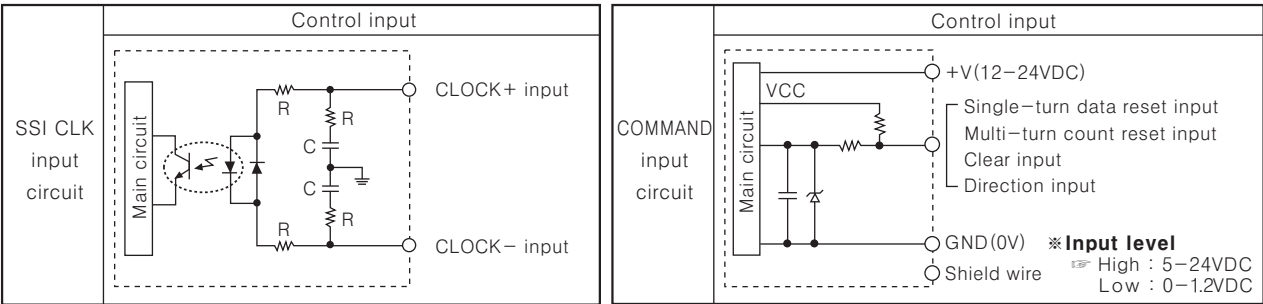


Parallel Interface 8192 revolution multi-turn count data output waveform (Binary code)



Control output I/O circuit

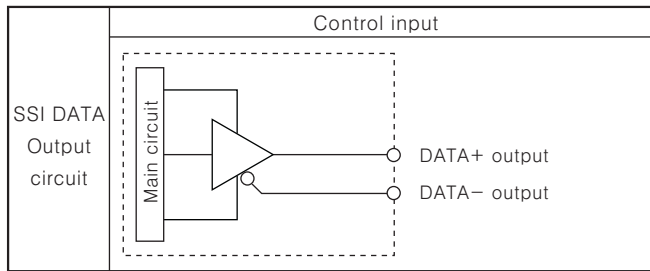
●SSI input • output



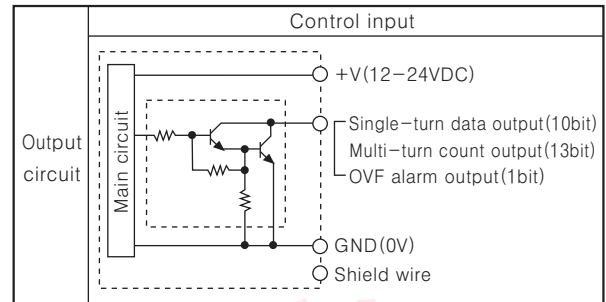
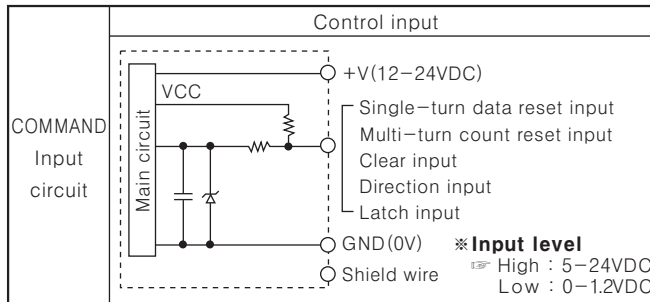
ϕ 50mm Shaft Multi-turn Absolute Type

■ Control output I/O circuit

● SSI output



● Parallel input • output



- ※ Output of each bit is the same circuit.
- ※ Overload or short may cause circuit break.

■ Connections

● SSI output

Cable			
Cable color	Description	Cable color	Description
Brown	CLOCK+	Gray	Single-turn data reset
Red	CLOCK-	Blue	Multi-turn count reset
Orange	DATA+	Purple	Clear
Yellow	DATA-	Green	Direction
White	+V (12-24VDC)		
Black	GND (0V)		
Shield wire	Signal shield cable(F.G)		

● Parallel output

Multi-turn count cable(Sheath color : Black)			Single-turn data cable(Sheath color : Gray)		
Cable color	Description		Cable color	Description	
Brown	Multi-turn count	2 ⁰	Brown	Single-turn data	2 ⁰
Red		2 ¹	Red		2 ¹
Orange		2 ²	Orange		2 ²
Yellow		2 ³	Yellow		2 ³
Green		2 ⁴	Green		2 ⁴
Blue		2 ⁵	Blue		2 ⁵
Purple		2 ⁶	Purple		2 ⁶
Gray		2 ⁷	Gray		2 ⁷
Pink		2 ⁸	Pink		2 ⁸
Clear		2 ⁹	Clear		2 ⁹
Light brown		2 ¹⁰	Light brown	NC	
Light yellow		2 ¹¹	Light yellow	Direction	
Light green		2 ¹²	Light green	Latch	
Light blue	OVF		Light blue	Clear	
Light purple	Multi-turn count reset		Light purple	Single-turn data reset	
White	+V(12-24VDC)		White	+V(12-24VDC)	
Black	GND(0V)		Black	GND(0V)	
Shield wire	Signal shield cable(F.G)		Shield wire	Signal shield cable(F.G)	

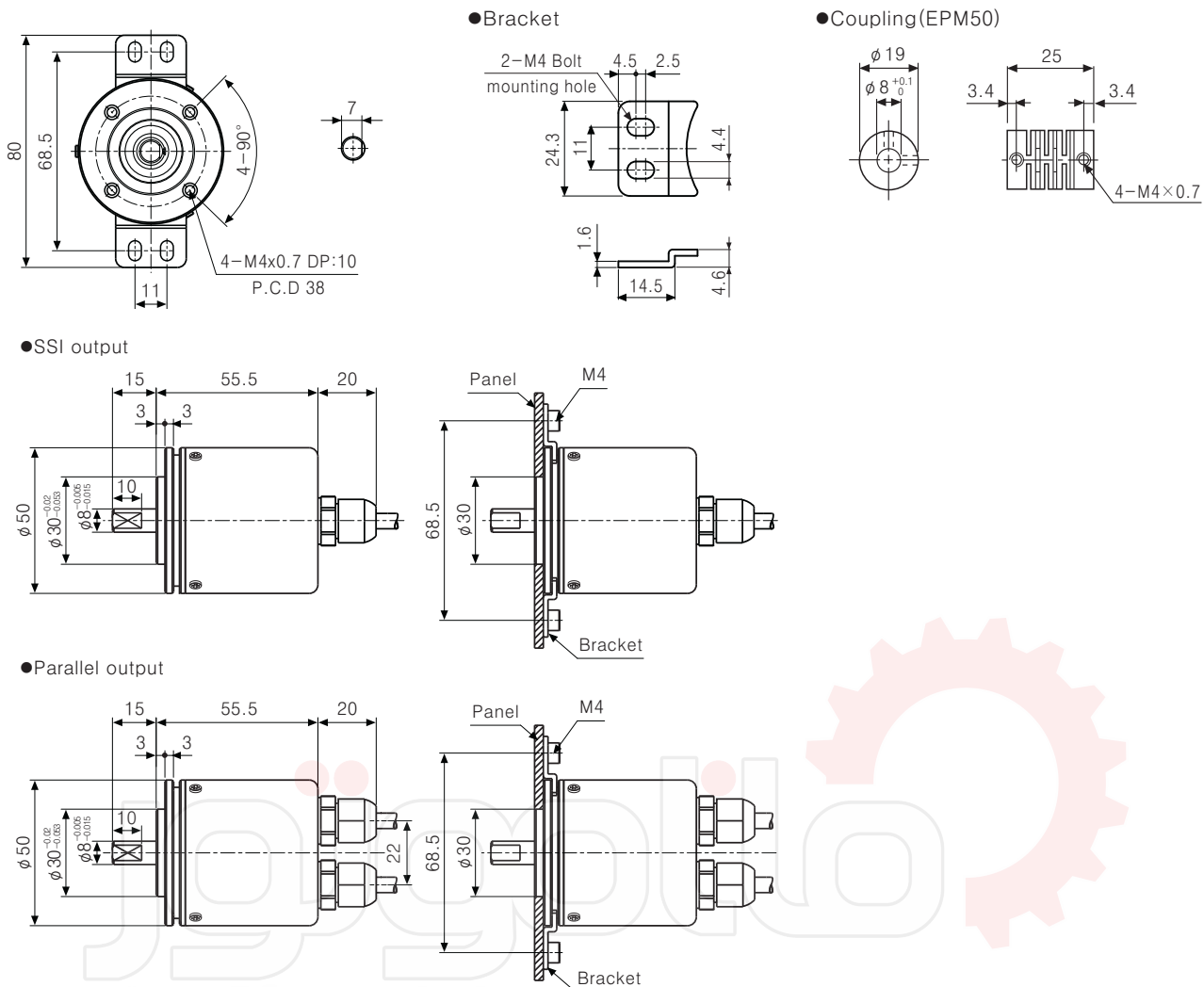
- ※ Please wire properly.
- ※ As for parallel output, it is recommended to connect +V and GND of both multi-turn count cable and single-turn data cable.
- ※ The metal case and shield wire of encoder should be grounded (F.G).
- ※ Input/Output cable must not be short-circuited, because Driver IC is used in output circuit.

- (A) Photo electric sensor
- (B) Fiber optic sensor
- (C) Door/Area sensor
- (D) Proximity sensor
- (E) Pressure sensor
- (F) Rotary encoder
- (G) Connector/Socket
- (H) Temp. controller
- (I) SSR/Power controller
- (J) Counter
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- (L) Panel meter
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EPM50 SERIES

■ Dimensions

(Unit:mm)



■ Functions

◎Single-turn data reset

Single-turn data will be initialized as 「0」 when GND (Low level) is input over 100ms on single-turn data reset line. In case of not using single-turn data reset line, connect the line to OPEN or +V (High level).

◎Multi-turn count reset

Multi-turn data will be initialized as 「revolution 0」 when GND(Low level) is input over 100ms on multi-count reset line. In case of not using multi-turn count reset line, connect the line to OPEN or + V (High level). OVF alarm will be initialized with multi-turn count reset input.

◎Clear

Single-turn data will be initialized as 「0」 and multi-count will be also initialized as 「revolution 0」 when GND (Low level) is input over 100ms on Clear line. In case of not using clear line, connect the line to OPEN or + V (High level). OVF alarm will be initialized with clear input.

◎Direction

Connect Direction line to OPEN or +V (High level) and turn on the power. Output will increase when rotation direction is CW from shaft axis. In case of connecting to GND(Low level), output will increase when rotation direction is CCW. If direction setting is reset, single-turn data, multi-turn count and OVF will be reset together since direction setting is initial setting which is set with Power ON.

◎Latch(Parallel output model only)

When connecting latch line to GND(Low level) over 500μs, outputs for single-turn data, multi-turn count and OVF at latch point will be remained. When latch line is connected to OPEN or +V (High level), output will be returned to operating mode output.

◎OVF

It is an alarm function providing output when multi-turn count is out of rotation ranges(0 to 8191 revolutions). OVF will be initialized through direction setting change, multi-turn count reset or clear input.